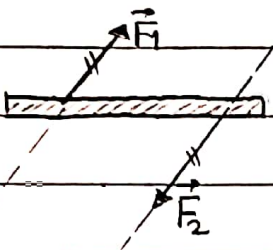


ΘΕΜΑ Α (Επαναληπτικές Νέο)

A1. $V_{\text{eff}} = \frac{V_{\text{max}}}{\sqrt{2}} = \frac{100 \text{ V}}{\sqrt{2}} \Rightarrow V_{\text{eff}} = 50\sqrt{2} \text{ V} \rightarrow \textcircled{\gamma}$

A2. $T_{\delta} = \frac{1}{f_2 - f_1} = \frac{1}{4} \text{ sec} \rightarrow \Delta t = 1 \text{ sec} = 4 \cdot T_{\delta} \rightarrow \textcircled{\beta}$

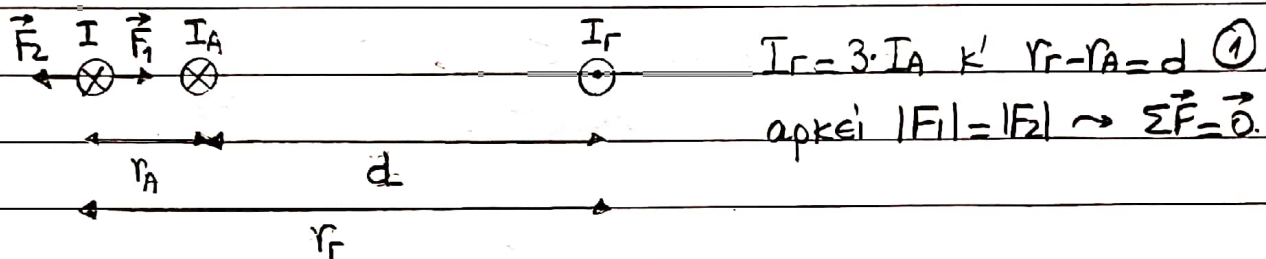
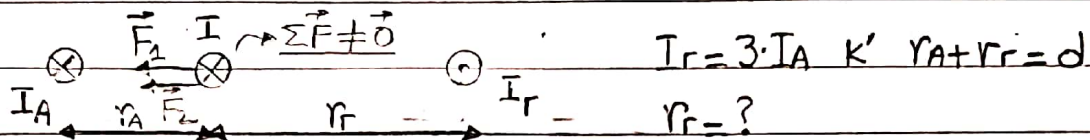
A3.  $\rightarrow \Sigma \vec{F} = \vec{0}$ κ' $\Sigma \vec{\tau}_{\text{cm}} \neq \vec{0} \rightarrow \textcircled{\delta}$

A4. $\Sigma \vec{F}_{\text{ext}} = \vec{0} \Rightarrow \vec{p} \omega = \text{σταθ. με } K_{\text{ΠΡΙΝ}} \leq K_{\text{ΜΕΤΑ}} \text{ γενικά} \rightarrow \textcircled{\alpha}$

A5. α.Σ, β.Σ, γ.Λ, δ.Λ, ε.Λ

ΘΕΜΑ Β (Επαναληπτικές Νέο)

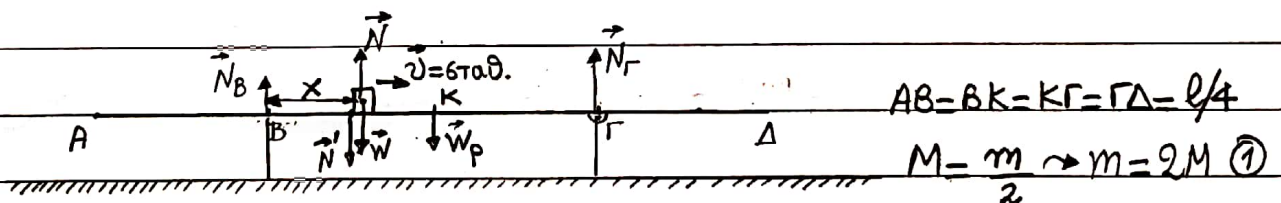
B1.



$$\text{Άρα: } k_{\mu} \frac{2I \cdot I_A \cdot l}{r_A} = k_{\mu} \cdot \frac{2I \cdot I_R \cdot l}{r_R} \Rightarrow \frac{I_A}{r_A} = \frac{3I_A}{r_R} \Rightarrow r_R = 3 \cdot r_A \text{ ②}$$

$$\text{① κ' ②} \Rightarrow r_R - \frac{r_R}{3} = d \Rightarrow \frac{2}{3} r_R = d \Rightarrow r_R = \frac{3d}{2} \rightarrow \text{ii}$$

B2.



$$\Sigma \vec{F}_m = \vec{0} \Rightarrow mg = N, N' = N \text{ 3ος Ν.Ν.} \rightarrow N' = mg \text{ ②.}$$

$$\Sigma \vec{\tau}_R = \vec{0} \xrightarrow{\text{+}} -N_B \cdot \frac{2l}{4} + N' \cdot \left(\frac{2l}{4} - x\right) + Mg \cdot \frac{l}{4} = 0 \xrightarrow{\text{②}}$$

$$\Rightarrow 2M \cdot g \cdot \left(\frac{2l}{4} - x\right) + Mg \cdot \frac{l}{4} = N_B \cdot \frac{2l}{4} \Rightarrow 5 \cdot Mg \cdot \frac{l}{4} - 2Mg \cdot x = N_B \cdot \frac{2l}{4} \Rightarrow$$

$$\Rightarrow 2.5Mg - 4Mg \cdot \frac{x}{l} = N_B \xrightarrow{N_B \geq 0} 2.5 \geq 4 \cdot \frac{x}{l} \Rightarrow x_{\max} = \frac{5}{8} \cdot l$$

$$\text{Είπαμε: } x_{\max} = v \cdot t_1 \Rightarrow t_1 = \frac{5 \cdot l}{8 \cdot v} \rightarrow \text{iii}$$

B3.

Γενικά για την οριζόντια βολή έχουμε:

$$\left. \begin{aligned} x &= v_{EK} \cdot t \\ y &= \frac{1}{2} g \cdot t^2 \end{aligned} \right\} \Rightarrow y = \frac{g}{2 \cdot v_{EK}^2} \cdot x^2 \quad (1)$$

$$\Theta. \text{ Torricelli : } v_{EK1} = \sqrt{2g \cdot (H-h_1)} \quad \text{κ' } v_{EK2} = \sqrt{2g \cdot (H-h_2)} \quad (2)$$

$$\text{Εί υποθέσουμε έχουμε ίσα βεληνεκή : } x_1 = x_2. \quad (3)$$

$$\left. \begin{aligned} \text{Τότε (1), (2)} &\Rightarrow h_1 = \frac{g}{2 \cdot 2g(H-h_1)} \cdot x_1^2 \\ &\vdots \\ \text{κ' } h_2 &= \frac{g}{2 \cdot 2g(H-h_2)} \cdot x_2^2 \end{aligned} \right\} \xrightarrow{(3)} \Rightarrow$$

$$\Rightarrow \frac{h_1}{h_2} = \frac{H-h_2}{H-h_1} \Rightarrow h_1 \cdot H - h_1^2 = h_2 \cdot H - h_2^2 \Rightarrow$$

$$\Rightarrow (h_2 - h_1) \cdot (h_2 + h_1) = H \cdot (h_2 - h_1) \Rightarrow H = h_1 + h_2 \rightarrow (i)$$

ΘΕΜΑ Γ (Ερωτασθηπικες Νέο)

ΚΑ: $m = 0.2 \text{ kg}$, $l = 1 \text{ m}$, $R_2 = 6 \Omega$, $B = 2 \text{ T} \otimes$

$$R_1 = 2 \Omega$$

$$R_{\text{ολ}} = 8 \Omega$$

$t = 0 \text{ sec}$: $v_0 = 12 \text{ m/s} \downarrow$

Γ1. $|a_0| = ? \rightarrow t = 0 \text{ sec}$

$$|F_0| = \frac{B^2 \cdot l^2}{R_{\text{ολ}}} \cdot |v_0| = 6 \text{ N} \uparrow, \quad |W| = m \cdot |g| = 2 \text{ N} \downarrow$$

άρα $|a_0| = \frac{|F_0| - |W|}{m} = 20 \text{ m/s}^2$ κ' $\vec{a}_0 \uparrow$ επιβραδυνόμενη.

Γ2. $v_{\text{op}} = ?$

$$\Sigma F = 0 \text{ όταν } v = v_{\text{op}} \rightarrow \frac{B^2 \cdot l^2}{R_{\text{ολ}}} \cdot |v_{\text{op}}| = mg \Rightarrow$$

$$\Rightarrow |v_{\text{op}}| = \frac{m \cdot g \cdot R_{\text{ολ}}}{B^2 \cdot l^2} \Rightarrow |v_{\text{op}}| = 4 \text{ m/s}$$

$$\text{Έλεγχος: } \tau = \frac{m \cdot R_{\text{ολ}}}{B^2 \cdot l^2} = 0.4 \text{ sec} \rightarrow |v_{\text{op}}| = g \cdot \tau$$

$$\Sigma F = m \cdot a \rightarrow \tau \cdot \dot{v} + v = v_{\text{op}} \rightarrow v = v_{\text{op}} - (v_{\text{op}} - v_0) \cdot e^{-t/\tau} \rightarrow$$

$$\rightarrow y = v_{\text{op}} \cdot t + (v_{\text{op}} - v_0) \cdot \tau \cdot (e^{-t/\tau} - 1)$$

$$t_{\text{op}} = 5 \cdot \tau \rightarrow y_{\text{op}} = (4 \cdot v_{\text{op}} + v_0) \cdot \tau = \underline{11.2 \text{ m}}$$

$$\text{Τότε: } q_{\text{en}} = \frac{B \cdot l \cdot y_{\text{op}}}{R_{\text{ολ}}} = \underline{2.8 \text{ Cb}}$$

Γ3. $q_{\text{en}} = 0.4 \text{ Cb}$ από $t_0 = 0 \rightarrow t_1 = t_{\text{op}} \rightarrow Q_1 = ?$, $Q_2 = ?$

Λύουμε για : $q_{en} = 0.4cb \leadsto \gamma_{op} = \frac{q_{en} R_0}{8 \cdot l} = 1.6m$

$\Delta E : \frac{1}{2} m \cdot v_0^2 + mg \cdot \gamma_{op} - Q = \frac{1}{2} m \cdot v_{op}^2 \Rightarrow$

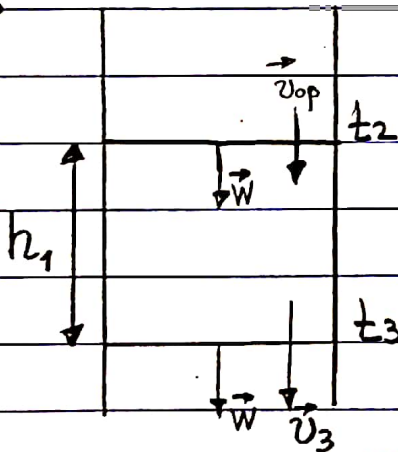
$\Rightarrow Q = \frac{m}{2} \cdot (v_0^2 - v_{op}^2) + m \cdot g \cdot \gamma_{op} \Rightarrow Q = 16j$

Για $\Delta t : \left. \begin{array}{l} \Delta Q_1 = I^2 \cdot R_1 \cdot \Delta t \\ \Delta Q_2 = I^2 \cdot R_2 \cdot \Delta t \end{array} \right\} \leadsto \frac{Q_1}{Q_2} = \frac{R_1 \cdot \sum I^2 \cdot \Delta t}{R_2 \cdot \sum I^2 \cdot \Delta t} \Rightarrow \frac{Q_1}{Q_2} = \frac{R_1}{R_2} = \frac{1}{3}$

$Q = Q_1 + Q_2 \Rightarrow Q = 4Q_1 \Rightarrow Q_1 = \frac{Q}{4} = 4j \text{ κ' } Q_2 = 12j$

Γ4.

$h_1 = 0.45m. \leadsto t_3 : \frac{dK}{dt} = ?$



$\left. \begin{array}{l} \Sigma \vec{F} = m \cdot \vec{g} \Rightarrow \vec{a} = \vec{g} \\ \frac{dK}{dt} = \Sigma \vec{F} \cdot \vec{v}_3 \end{array} \right\} \Rightarrow$

$\Rightarrow \frac{dK}{dt} = + m \cdot |g| \cdot |v_3|$

ΘΜΚΕ : $\frac{m}{2} \cdot (v_3^2 - v_{op}^2) = + mg \cdot h_1 \Rightarrow |v_3| = \sqrt{v_{op}^2 + 2gh_1} = 5m/s$

$\Rightarrow \frac{dK}{dt} = + 10j/s$

ΘΕΜΑ Δ (Σημειολογική Νέο)

$$\Sigma_1: m_1 = 5 \text{ kg}, k_1 = 80 \text{ N/m} \rightarrow \omega_1 = \sqrt{\frac{k_1}{m_1}} = 4 \text{ rad/s}$$

$$\Sigma_2: m_2 = 12 \text{ kg}, k_2 = 300 \text{ N/m} \rightarrow \omega_2 = \sqrt{\frac{k_2}{m_2}} = 5 \text{ rad/s}$$

$$\Theta I_1 \xleftrightarrow{d} \Theta I_2 : d = 0.6 \text{ m}$$

$$\Delta 1. \omega_1 = 4 \text{ rad/s} \rightarrow T_1 = 2\pi/\omega_1 = 2\pi/4 \text{ sec} = 10\pi/20 \text{ sec}$$

$$\omega_2 = 5 \text{ rad/s} \rightarrow T_2 = 2\pi/\omega_2 = 2\pi/5 \text{ sec} = 8\pi/20 \text{ sec}$$

$$d_1 = 0.6 \text{ m} (\leftarrow) \text{ κ' } v_0 = 0 \Rightarrow A_1 = d_1 = 0.6 \text{ m}$$

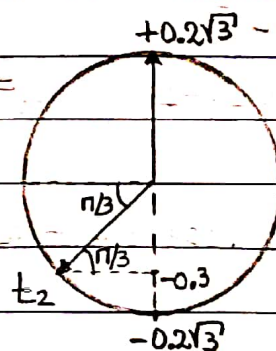
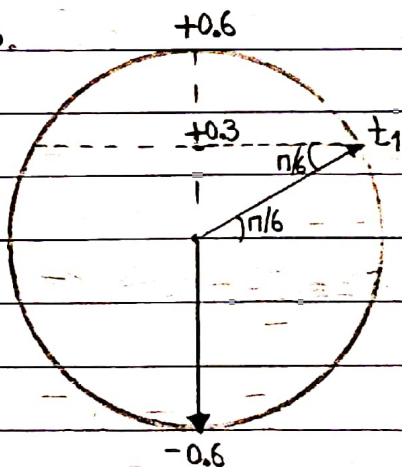
$$d_2 = 0.2\sqrt{3} \text{ m} (\rightarrow) \text{ κ' } v_0 = 0 \Rightarrow A_2 = d_2 = 0.2\sqrt{3} \text{ m}$$

$$\Delta 2. \text{ Είναι } \phi_{01} = \frac{3\pi}{2} \text{ κ' } \phi_{02} = \frac{\pi}{2} \text{ επομένως:}$$

$$x_1 = 0.6 \cdot \eta\mu(4t + 3\pi/2) \text{ (1a)}, \quad v_1 = 2.4 \cdot \sigma\upsilon\nu(4t + 3\pi/2) \text{ (1b)} \quad \text{SI}$$

$$x_2 = 0.2\sqrt{3} \cdot \eta\mu(5t + \pi/2) \text{ (2a)}, \quad v_2 = \sqrt{3} \cdot \sigma\upsilon\nu(5t + \pi/2) \text{ (2b)}$$

Δ3.



$$t_1 = \frac{T_1}{4} + \frac{T_1}{12} = \frac{T_1}{3} = \frac{2\pi \text{ sec}}{12}, \quad t_2 = \frac{T_2}{4} + \frac{2T_2}{12} = \frac{5 \cdot T_2}{12} = \frac{2\pi \text{ sec}}{12}$$

$$\text{όρα } t_1 = t_2 = 2\pi/12 \text{ sec} = \pi/6 \text{ sec} = t_{\text{kr}}$$

ΘΕΜΑ Δ (Επαναληπτικές Νέο).

$$\Sigma_1: m_1 = 5 \text{ kg}, k_1 = 80 \text{ N/m} \rightarrow \omega_1 = \sqrt{\frac{k_1}{m_1}} = 4 \text{ r/s}$$

$$\Sigma_2: m_2 = 12 \text{ kg}, k_2 = 300 \text{ N/m} \rightarrow \omega_2 = \sqrt{\frac{k_2}{m_2}} = 5 \text{ r/s}$$

$$\Theta I_1 \xleftrightarrow{d} \Theta I_2 : d = 0.6 \text{ m}$$

$$\Delta 1. \omega_1 = 4 \text{ r/s} \rightarrow T_1 = 2\pi/\omega_1 = 2\pi/4 \text{ sec} = 10\pi/20 \text{ sec}$$

$$\omega_2 = 5 \text{ r/s} \rightarrow T_2 = 2\pi/\omega_2 = 2\pi/5 \text{ sec} = 8\pi/20 \text{ sec}$$

$$d_1 = 0.6 \text{ m} (\leftarrow) \text{ κ' } v_0 = 0 \Rightarrow A_1 = d_1 = 0.6 \text{ m}$$

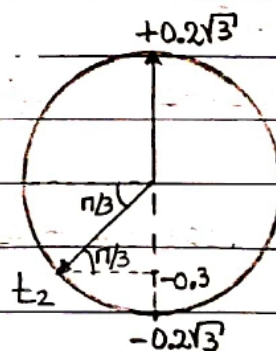
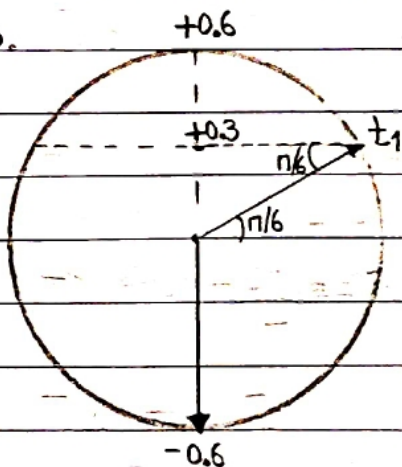
$$d_2 = 0.2\sqrt{3} \text{ m} (\rightarrow) \text{ κ' } v_0 = 0 \Rightarrow A_2 = d_2 = 0.2\sqrt{3} \text{ m}$$

$$\Delta 2. \text{ Είναι } \phi_{01} = \frac{3\pi}{2} \text{ r κ' } \phi_{02} = \frac{\pi}{2} \text{ r επομένως:}$$

$$x_1 = 0.6 \cdot \eta\mu(4t + 3\pi/2) \text{ (1a)}, \quad v_1 = 2.4 \cdot \sigma\upsilon\nu(4t + 3\pi/2) \text{ (1b)} \quad \text{SI}$$

$$x_2 = 0.2\sqrt{3} \cdot \eta\mu(5t + \pi/2) \text{ (2a)}, \quad v_2 = \sqrt{3} \cdot \sigma\upsilon\nu(5t + \pi/2) \text{ (2b)}$$

$\Delta 3.$



$$t_1 = \frac{T_1}{4} + \frac{T_1}{12} = \frac{T_1}{3} = \frac{2\pi \text{ sec}}{12}, \quad t_2 = \frac{T_2}{4} + \frac{2T_2}{12} = \frac{5 \cdot T_2}{12} = \frac{2\pi \text{ sec}}{12}$$

$$\text{άρα } t_1 = t_2 = 2\pi/12 \text{ sec} = \pi/6 \text{ sec} = t_{\text{kr}}$$

Δ4. την $t_{kp} = \frac{\pi}{6} \text{ sec}$ έχουμε:

$$(18): v_1 = 2.4 \sin\left(\frac{4\pi}{6} + \frac{3\pi}{2}\right) = 2.4 \cdot \sin\left(\frac{13\pi}{6}\right) \Rightarrow$$

$$v_1 = 2.4 \sin\left(2\pi + \frac{\pi}{6}\right) \Rightarrow v_1 = 1.2\sqrt{3} \text{ m/s } (\rightarrow)$$

$$(26): v_2 = \sqrt{3} \cdot \sin\left(\frac{5\pi}{6} + \frac{\pi}{2}\right) = \sqrt{3} \cdot \sin\left(\frac{4\pi}{3}\right) \Rightarrow$$

$$v_2 = \sqrt{3} \cdot \sin\left(\pi + \frac{\pi}{3}\right) \Rightarrow v_2 = -0.5\sqrt{3} (\leftarrow)$$

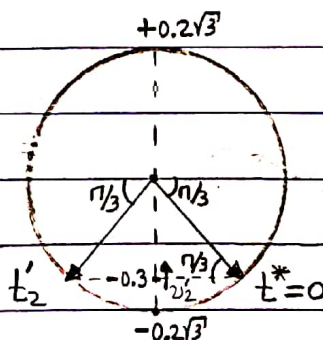
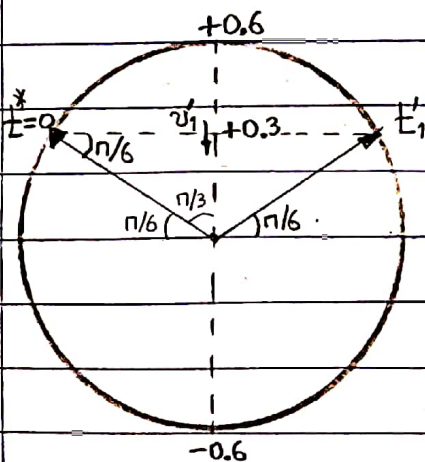
Ελαστική κρούση: $v'_1 = \frac{2m_2 \cdot v_2 + (m_1 - m_2) \cdot v_1}{m_1 + m_2} \Rightarrow$

$$\Rightarrow v'_1 = \frac{-12\sqrt{3} + (-7) \cdot 1.2\sqrt{3}}{17} \text{ m/s} \Rightarrow v'_1 = -1.2\sqrt{3} \text{ m/s. } (\leftarrow)$$

$$K' \quad v_1 + v'_1 = v_2 + v'_2 \Rightarrow (+1.2\sqrt{3} - 1.2\sqrt{3}) \text{ m/s} = -0.5\sqrt{3} \text{ m/s} + v'_2 \Rightarrow$$

$$\Rightarrow v'_2 = +0.5\sqrt{3} \text{ m/s } (\rightarrow)$$

Δ5. Έχουμε $|v'_1| = |v_1| \Rightarrow A_1 = 0.6 \text{ m}$ } δεν αλλάζουν
και $|v'_2| = |v_2| \Rightarrow A_2 = 0.2\sqrt{3} \text{ m}$



$$t'_1 = \frac{T_1}{2} + \frac{T_1}{6} = \frac{2T_1}{3} = \frac{\pi}{3} \text{ sec} \quad K' \quad t'_2 = \frac{T_2}{2} + \frac{T_2}{3} = \frac{5T_2}{6} = \frac{\pi}{3} \text{ sec}$$

$$t'_1 = t'_2 = \frac{\pi}{3} \text{ sec} = t'_{kp}$$